



AVERAGING OF THE SYSTEM OF EQUATIONS OF MOTION OF A VISCOUS FLUID IN A POROUS MEDIUM†

G. P. PANASENKO

Moscow

(Received 26 May 1993)

A system of equations of motion of a viscous fluid (with a small coefficient of viscosity) in a periodic porous medium is considered. The ratio of the period of the structure of the medium to the characteristic dimension of the problem is a small parameter. The pore size and period of the structure are of the same order of magnitude. A formal asymptotic solution is constructed and an averaged equation, which is an analogue of the Boussinesq equation, is derived.

We will adopt as a model of a porous system a continuous medium with periodically arranged cavities (see [1], for example). Let K be the cube $\{\xi \in \mathbb{R}^3 \mid 0 < \xi_j < 1, j = 1, 2, 3\}$ and let us place a certain set, consisting of a finite number of domains, in K and continue it periodically (with a period of unity) in the whole of the space \mathbb{R}^3 . Let A be the union of all the resulting sets. We assume that the boundary ∂A is a smooth manifold and the domain $\Omega = \mathbb{R}^3 \setminus A$ is connected, and that A_ϵ is the set obtained from A by a homothetic contraction ϵ^{-1} times (ϵ is a small parameter), that is, $A_\epsilon = \{x \in \mathbb{R}^3 \mid x/\epsilon \in A\}$.

We will adopt as the geometric model of the pore system the domain $\Omega_\epsilon = \mathbb{R}^3 \setminus A_\epsilon$ and consider the system of equations of motion of a viscous fluid with a small coefficient of viscosity μ_ϵ in this set

$$\begin{aligned} \rho(\partial v / \partial t + (v, \nabla)v) &= -\nabla p + \mu_\epsilon \Delta v + f_\epsilon(x / \epsilon, x, t, v) \\ \partial \rho / \partial t + \operatorname{div}(\rho v) &= 0, \quad \rho = Q(p), \quad \rho, v \in \mathbb{R}^3 \\ \mu_\epsilon &= \epsilon^\gamma \mu, \quad \gamma < 2, \quad \mu = \text{const}, \quad f_\epsilon(\xi, x, t, v) = f(\xi, x, \epsilon^{2-\gamma}, v) \end{aligned} \tag{1}$$

$x \in \Omega_\epsilon$ and $t > 0$ (ρ is the density, v is the velocity vector and p is the pressure), $f(\xi, x, \tau, v)$ and μ are independent of ϵ , the function f is 1-periodic with respect to $\xi \in \Omega$, and Q is a specified smooth function.

The no-slip condition

$$v|_{\partial \Omega_\epsilon} = 0 \tag{2}$$

is imposed at the boundary of the domain Ω_ϵ and the initial values of the unknown functions

$$t = 0: \quad v = 0, \quad p = 0 \tag{3}$$

are specified.

The limiting behaviour of the solution of problem (1)–(3) as $\epsilon \rightarrow 0$ is studied (a formal asymptotic solution is constructed).

There is an extensive literature ([2–8], for example) on the investigation of various equations defined in domains of this type. In particular, systems of Stokes and Navier–Stokes equations in porous media have been considered in [5–8] and averaged models of the Darcy law type [5–8], of the non-linear Darcy law type [8] and also the Brinkman law type [9] have been obtained. An averaged model of the Boussinesq equation type [10] will be obtained below for problem (1)–(3).

A formal asymptotic solution is sought in the form of functions of fast and slow variables

$$\begin{aligned} v &= \epsilon^{2-\gamma} (\bar{v}(x, \tau) + V(x / \epsilon, x, \tau)) \\ p &= \bar{p}(x, \tau) + \epsilon P(x / \epsilon, x, \tau), \quad \rho = \bar{\rho}(x, \tau) + \epsilon R(x / \epsilon, x, \tau) \\ \tau &= \epsilon^2 t - \gamma, \quad \langle V \rangle = \int_{K \setminus A} V(\xi, x, \tau) d\xi = 0 \end{aligned} \tag{4}$$

†Prikl. Mat. Mekh. Vol. 59, No. 2, pp. 340–343, 1995.

where $P(\xi, x, \tau)$, $V(\xi, x, \tau)$, $R(\xi, x, \tau)$ are 1-periodic functions of ξ .

Substituting (4) into (1) and using the formula for the differentiation of a complex function, we obtain

$$\begin{aligned}
 & -\mu\Delta_\xi V + \nabla_x \bar{p} + \nabla_\xi P - f(\xi, x, \tau, \varepsilon^{2-\gamma}(\bar{u} + V)) + \varepsilon^{3-2\gamma} \bar{\rho}(\bar{u} + V) \nabla_\xi V + \\
 & + \varepsilon^{2(2-\gamma)} (\bar{\rho} \partial(\bar{u} + V) / \partial \tau + R(\bar{u} + V) \nabla_\xi V + (\bar{p} + \varepsilon R)(\bar{u} + V) \nabla_x(\bar{u} + V)) +
 \end{aligned} \tag{5}$$

$$\begin{aligned}
 & + \varepsilon^{5-2\gamma} R \partial(\bar{u} + V) / \partial \tau + \varepsilon(\nabla_x P - 2\mu\Delta_{x\xi} V) - \varepsilon^2 \mu \Delta_x(\bar{u} + V) - h\bar{u} - \bar{h}(x, \tau) = 0 \\
 & \varepsilon^{-1} \operatorname{div}_\xi(\bar{\rho} V) + \partial \bar{p} / \partial \tau + \operatorname{div}_x(\bar{\rho}(\bar{u} + V)) + \operatorname{div}_\xi(R(\bar{u} + V)) + \varepsilon(\partial R / \partial \tau + \operatorname{div}_x(R(\bar{u} + V)))
 \end{aligned} \tag{6}$$

$$\bar{p} - Q(\bar{p}) + \varepsilon R - (Q(\bar{p} + \varepsilon P) - Q(\bar{p})) = 0 \tag{7}$$

$$\Delta_{x\xi} = \sum_{i=1}^3 \frac{\partial^2}{\partial x_i \partial \xi_i}$$

h is a constant 3×3 matrix, and $\bar{h}(x, \tau)$ is a vector function, chosen from the condition $\langle V \rangle = 0$.

On the boundary $\partial\Omega_\varepsilon$

$$\bar{u} + V = 0 \tag{8}$$

The functions \bar{p} , \bar{u} , $\bar{\rho}$, \bar{h} , P , V , R are sought in the form of regular series in the parameters $\varepsilon_1 = \varepsilon$, $\varepsilon_2 = \varepsilon^{3-2\gamma}$, $\varepsilon_3 = \varepsilon^{2-\gamma}$.

Substituting these series into Eqs (5)–(8), we obtain

$$\begin{aligned}
 & \sum_{k,l,m=0}^{\infty} \varepsilon_1^k \varepsilon_2^l \varepsilon_3^m (\nabla_x \bar{p}_{klm} + h\bar{u}_{klm} + \bar{h}_{klm}) + \sum_{k,l,m=0}^{\infty} \varepsilon_1^k \varepsilon_2^l \varepsilon_3^m (-\mu\Delta_\xi V_{klm} + \nabla_\xi P_{klm}) = 0 \\
 & \varepsilon^{-1} \sum_{k,l,m=0}^{\infty} \varepsilon_1^k \varepsilon_2^l \varepsilon_3^m (\operatorname{div}_\xi(\bar{\rho}_{000} V_{klm}) - \Phi_{klm}^1) = 0 \\
 & \bar{\rho}_{000} - Q(\bar{\rho}_{000}) + \sum_{\substack{k,l,m=0 \\ (k,l,m) \neq (0,0,0)}}^{\infty} \varepsilon_1^k \varepsilon_2^l \varepsilon_3^m \left((R_{klm} - \frac{\partial Q}{\partial p} \Big|_{p=\bar{\rho}_{000}} P_{klm} - \Phi_{klm}^3) + \right. \\
 & \left. + (\bar{p}_{k+1,l,m} - \frac{\partial Q}{\partial p} \Big|_{p=\bar{\rho}_{000}} P_{k+1,l,m}) \right) = 0
 \end{aligned} \tag{9}$$

$$V_{klm} = -v_{klm}, \quad \xi \in \partial\Omega$$

The three subscripts correspond to the number of the coefficient in the regular expansion in powers of ε_1 , ε_2 , ε_3 : Φ_{klm}^1 depends on $\bar{\rho}_{qsr}$, \bar{u}_{qsr} , \bar{p}_{qsr} , R_{qsr} , V_{qsr} , P_{qsr} with the subscripts q, s and r such that $q \leq k$, $s \leq l$, $r \leq m$, where just one of these inequalities is strict and Φ_{klm}^3 also depend on \bar{p}_{klm} .

Note that

$$\begin{aligned}
 & \langle \Phi_{0lm}^1 \rangle = 0, \quad \langle \Phi_{k+1,l,m}^1 \rangle = \partial \bar{p}_{klm} / \partial \tau + \operatorname{div}_x(\bar{p}_{klm} \bar{u}_{000} + \bar{\rho}_{000} \bar{u}_{klm}) + \\
 & + (\operatorname{div}_x(\bar{p}_{klm} V_{000}) + \operatorname{div}_x(\bar{\rho}_{000} V_{klm})) + \bar{\Psi}_{klm}(x, \tau)
 \end{aligned} \tag{10}$$

where $\bar{\Psi}_{klm}(x, \tau)$ also depend on $\bar{\rho}_{qsr}$, \bar{u}_{qsr} with the subscripts q, s , and r which satisfy the same inequalities as above, $(k, l, m) \neq (0, 0, 0)$.

The matrix h and the vector \bar{h}_{klm} are chosen from the condition

$$\langle V_{klm} \rangle = 0 \tag{11}$$

The coefficients \bar{p}_{klm} , \bar{u}_{klm} , $\bar{\rho}_{klm}$, \bar{h}_{klm} , V_{klm} , R_{klm} are constructed according to the following algorithm. Let $W(\xi)$ be a 3×3 matrix function and let $F(\xi)$ be a three-element row matrix, 1-periodic with respect to ξ , and a solution of the problem

$$-\mu\Delta_\xi W + \nabla_\xi F = E, \quad \operatorname{div}_\xi W = 0, \quad \xi \in \Omega \tag{12}$$

$$W = 0; \quad \xi \in \partial\Omega$$

E is the unit 3×3 matrix. Let us put

$$V_{klm} = W(h\bar{v}_{klm} + \tilde{h}_{klm}) + \tilde{V}_{klm} - \bar{v}_{klm} \tag{13}$$

where h and \tilde{h}_{klm} are chosen from the condition that $\langle V_{klm} \rangle = 0$, that is, $(V_{klm}, P_{klm}, R_{klm})$ is a solution of the problem

$$-\mu\Delta_{\xi} V_{klm} + \nabla_{\xi} P_{klm} = \Phi_{klm}^2, \quad \xi \in \Omega \tag{14}$$

$$\operatorname{div}_{\xi} (\rho_{000} V_{klm}) = \Phi_{klm}^1, \quad \xi \in \Omega \tag{15}$$

$$R_{klm} = \left. \frac{\partial Q}{\partial p} \right|_{p=\bar{p}_{000}} P_{klm} + \Phi_{klm}^3, \quad \xi \in \Omega \tag{16}$$

$$\tilde{V}_{klm} = 0, \quad \xi \in \partial\Omega \tag{17}$$

$$h = \langle W \rangle^{-1}, \quad \tilde{h}_{klm} = -\langle W \rangle^{-1} \langle \tilde{V}_{klm} \rangle \tag{18}$$

Actually, it follows from (13) and (18) that

$$\langle W(h\bar{v}_{klm} + \tilde{h}_{klm}) + \tilde{V}_{klm} - \bar{v}_{klm} \rangle = 0$$

The condition for problem (14), (15), (17) to be solvable [2, p. 167] is

$$\langle \Phi_{k+1lm}^1 \rangle = 0$$

and relations (9)–(11) yield the equations for $\bar{\rho}_{klm}, \bar{P}_{klm}, \bar{v}_{klm}$

$$h\bar{v}_{klm} + \tilde{h}_{klm} + \nabla_x \bar{P}_{klm} = 0 \tag{19}$$

$$\partial \bar{\rho}_{klm} / \partial \tau + \operatorname{div}_x (\bar{\rho}_{klm} \bar{v}_{000} + \bar{\rho}_{000} \bar{v}_{klm}) + \bar{\Psi}_{klm}(x, \tau) = 0$$

$$\bar{P}_{klm} = \left. \frac{\partial Q}{\partial p} \right|_{p=\bar{p}_{000}} \bar{P}_{klm}, \quad (k, l, m) \neq (0, 0, 0)$$

$$\langle \dot{W} \rangle^{-1} \bar{v}_{000} + \nabla \bar{P}_{000} - \langle W \rangle^{-1} \langle V_{000} \rangle = 0 \tag{20}$$

$$\partial \bar{\rho}_{000} / \partial \tau + \operatorname{div}_x (\bar{\rho}_{000} \bar{v}_{000}) = 0, \quad \bar{\rho}_{000} = Q(\bar{p}_{000})$$

with the homogeneous initial conditions $t = 0: \bar{P}_{klm} = 0, \bar{v}_{klm} = 0$.

System (20) is an averaged system of zeroth-order equations. Substituting v_{000} from the first equation and ρ_{000} from the third equation into the second equation, we obtain

$$\partial Q(\bar{p}_{000}) / \partial \tau - \operatorname{div}_x (Q(\bar{p}_{000}) \langle W \rangle (\nabla \bar{p}_{000} - \langle W \rangle^{-1} \langle \tilde{V}_{000} \rangle)) = 0 \tag{21}$$

where \tilde{V}_{000} is the solution of the problem

$$-\mu\Delta_{\xi} V_{000} + \nabla_{\xi} P_{000} = f(\xi, x, \tau, 0), \quad \xi \in \Omega$$

$$\operatorname{div}_{\xi} V_{000} = 0, \quad \xi \in \Omega; \quad V_{000}|_{\partial\Omega} = 0 \tag{22}$$

Equations (14)–(20) have to be solved in the following order: problem (14), (15), (17) is first solved for the pair \tilde{V}_{klm}, P_{klm} for each fixed set of k, l, m (when $(k, l, m) = (0, 0, 0)$, it is problem (22)). We next determine \tilde{h}_{klm} from (18) and then solve problems (19), (20) and, finally, R_{klm} is determined from (16).

We note that the averaged model (21), (22) is an analogue of the Boussinesq model: it becomes the Boussinesq model [10] in the case of a linear dependence of $Q(p)$. If $f(\xi, x, \tau, 0) = 0$ when $\tau \in [0, \tau_0], \tau_0 > 0$, it can be shown by induction that $\tilde{V}_{klm} = 0$ when $\tau \in (0, \tau_0)$ so that $\bar{v} + V$ are asymptotically equal to zero when $t = 0$. Conditions (1)–(3) are exactly satisfied asymptotically.

By analogy with problem (1) in the domain Ω_{ϵ} , problem (1)–(3) may be treated in the domain $G_{\epsilon} \times R$, where $G_{\epsilon} = \{x' \in R^2, x'/\epsilon \in G_1\}$, the domain G_1 is bounded in R^2 with a piecewise-smooth boundary, $x' = (x_1, x_2)$, the function f_{ϵ} is solely dependent on $x'/\epsilon, x_3, t, v$ and its first two components $f_{\epsilon 1}, f_{\epsilon 2}$ are zero.

This model simulates the motion of a viscous fluid in a channel of complex form. In constructing the asymptotic form we use (4) with x/ϵ replaced by $x'/\epsilon, x$ replaced by x_3 and $\bar{v} = (0, 0, \bar{v}_3)^*$. The analogue of the operator for the mean $\langle \cdot \rangle$ is the integral $\int_{G_1} \cdot \delta \xi', \xi' = (\xi_1, \xi_2)$ (the third component of the vectors $\langle V_{klm} \rangle$ is equal to zero).

The procedure which has been described above as applied to problem (1)–(3), in the first approximation yields

$$\frac{\partial Q(\bar{p}_{000})}{\partial \tau} - \frac{\partial}{\partial x_3} (Q(\bar{p}_{000}) \langle \hat{W} \rangle) \left(\frac{\partial \bar{p}_{000}}{\partial x_3} - \langle \hat{W} \rangle^{-1} \langle \hat{V}_{000} \rangle \right) = 0, \quad \bar{p}_{000}|_{\tau=0} = 0$$

in the domain $G_\varepsilon \times R$, where $\hat{W}(\xi')$ is the solution of Poisson's equation

$$-\mu \Delta_{\xi'} \hat{W} = 1, \quad \xi' \in G_1; \quad \hat{W}|_{\partial G_1} = 0$$

and $\hat{V}_{000}(\xi')$ is the solution of Poisson's equation

$$-\mu \Delta_{\xi'} \hat{V}_{000} = f^3(\xi', x_3, \tau, 0), \quad \xi' \in G_1, \quad \hat{V}_{000}|_{\partial G_1} = 0$$

Hence the homogenization procedure in the zeroth approximation yields an analogue of the Boussinesq equation in the case of an unsteady-state system of equations of motion for a viscous fluid with a small coefficient of viscosity.

This research was carried out with the financial support of the Russian Foundation for Basic Research (93-911-1729).

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Translated by E.L.S.